

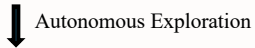
Existing Datasets (Bridge, OpenX, etc.)



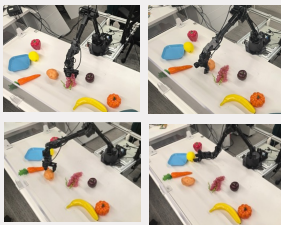
(a) Task-Irrelevant Trajectories



Real-World Deployment

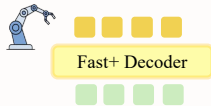


(b) Self-Exploration Trajectories



(A) What is Task-Agnostic Data?

Stage 1: Task-Agnostic Pretrain



$(o_t, o_{t+1})$

*“How to move”*

Stage 2: Task-Specific Alignment



*“push the pumpkin to the left”*

*“What to do”*

(B) Task-Agnostic Pretraining(TAP) framework